Home Exercises for the course "Identification of Parameters, Filtering, Prediction and Smoothing of Dynamic Models"

Exercise 1 Let us consider the following ARMA model

a

$$\left. \begin{array}{c} x_{n+1} = ax_n + bu_n + \zeta_n, \\ \zeta_n = \xi_n + d_1\xi_{n-1} + d_2\xi_{n-2}, \\ x_n, u_n, \zeta_n \in \mathbb{R}^1, \ n = 0, 1, \dots, \end{array} \right\}$$
(1)

with

$$= 0.5, \ b = 1, \ d_1 = 0.3, \ d_2 = -0.33, \\ x_0 = 5, \ u_n = \sin(0.3n),$$
 (2)

and $\{\xi_n\}_{n=0,1...}$ is a stationary sequence of independent Gaussian random variables satisfying

$$E \{\xi_n\} = 0, \ E \{\xi_n^2\} = \sigma^2 = 1, E \{\xi_n \xi_k\} \stackrel{n \neq k}{=} 0, \ E \{\xi_n x_n\} = 0, E \{\xi_n u_n\} = E \{\xi_{n-1} u_n\} = E \{\xi_{n-2} u_n\} = 0.$$
(3)

The model (1) can be represented in the generalized regression format as

$$\left\{\begin{array}{c}
x_{n+1} = c^{\mathsf{T}} z_n + \zeta_n, \\
c := \begin{pmatrix} a \\ b \end{pmatrix}, z_n := \begin{pmatrix} x_n \\ u_n \end{pmatrix} - \text{ generalized regression vector.} \end{array}\right\}$$
(4)

Problem: estimate the vector c using in each time n the observations (x_{n+1}, z_n) .

To do that let us apply the Instrumental Variable (IV) estimation algorithm

$$c_{n+1} = c_n + \Gamma_n v_n \left(x_{n+1} - z_n^{\mathsf{T}} c_n \right), \ c_0 = \begin{pmatrix} 0 \\ 0 \end{pmatrix}, \Gamma_n = \Gamma_{n-1} - \frac{\Gamma_{n-1} v_n z_n^{\mathsf{T}} \Gamma_{n-1}}{1 + z_n^{\mathsf{T}} \Gamma_{n-1} v_n}, \ z_n^{\mathsf{T}} \Gamma_{n-1} v_n \neq -1, \Gamma_0 = \rho^{-1} I_{2\times 2}, \ \rho = 10^{-5}.$$

$$(5)$$

Notice that

- for $v_n = z_n$ this is **Least Squares Method** (LSM);

- for $v_n = z_{n-2}$ this is **Instrumental Variables Method** (IVM); Show (by numerical simulations) that LSM method does not work in this example, but IVM correctly estimates unknown parameter c, namely,

$$c_n \xrightarrow[n \to \infty]{} c = \begin{pmatrix} 0.5 \\ 1 \end{pmatrix}.$$

Exercise 2