

Dynamic Neural Networks in Control Problems

(Redes Neuronales Dinámicas en Problemas de Control)

Dr. Alexander Poznyak

(Alexander Pozniak Gorbach)

Content of the 60-hours optional course

(contenido de 60 horas curso opcional)

September 12, 2023 – December 12, 2023

Each Tuesday (Martes) and Friday (Viernes) 13:00-15:00.

Presentation in English

1. **Introduction**
2. **ANN as computational artificial intelligence (AI) modeling instrument.**
 - 2.1. General concept of ANNs
 - 2.2. Static (Feedforward) ANNs
 - 2.3. Dynamic Neural Networks (DNNs).
 - 2.4. Some limitations of ANN.
3. **Particularities of DNNs**
 - 3.1. Design of the learning procedures
 - 3.2. The justification of the DifNNs structure
4. **Neural observer as a universal software sensor.**
 - 4.1. Uncertain system and the observer structures.
 - 4.2. Main assumptions
 - 4.3. Quasi-linear format of models
 - 4.4. Neuro-observer (software-sensor) structure
 - 4.5. Learning law for weights adaptation
5. **Estimation quality of a DNN non-parametric modeling**
 - 5.1. Definition of an ellipsoid
 - 5.2. Zone convergence of state estimation error by DNNO based on the ellipsoid technique.
6. **Adaptive controllers based on DNN estimates**

6.1	Separation principle
6.2	Average cost functions and locally-optimal control
6.3	Projectional Observers of Nonlinear Systems
6.4	Sliding Mode Control (SMC)
6.5	Backstepping control
7.	DNN control of mechanical systems
7.1	DNN control for Lagrange systems given in the general format
7.2	2-link robot-manipulator with DNN controller
7.3	ASG-DNN controller of the robotic arm with a pilot's cabin on the end-effector (motion cueing control)
7.4	Dynamic Motion Backstepping DNN Control of Underwater Autonomous Vehicle
8.	Differential Neural Networks Prediction Using Slow and Fast Hybrid Learning
8.1	Causal Approximation of prediction in dynamic models
8.2	DNN Predictor with Slow and Fast Components
8.3	Application to Prognosis of Infections and Deaths of COVID-19 Dynamics
9.	Application of Dynamic Neural Networks to Environment- Oriented biotechnological systems (a short excursion)
9.1.	Different types of bioreactors and fermentation regimes
9.1.1.	Batch regimen
9.1.2.	Semi-batch regimen
8.1.3.	Continuous regimen
9.2.	Microorganisms metabolism
9.2.1	Types of metabolic activities
9.4.	Adaptive ANN control for biotechnological processes
10.	Application of neural networks to environment-oriented chemical processes (a short excursion)

10.1. Photolysis	
10.2. Catalysis	
10.3. Ozonation	
10.4. Catalytic ozonation	

Recommended bibliography

1. Poznyak A, Sanchez E, Yu W (2001), *Differential neural networks for robust nonlinear control: identification, state estimation, and trajectory tracking*. World Scientific, Singapore.
2. Poznyak T, Chairez I, Poznyak A (2019), *Ozonation and biodegradation in environmental engineering: dynamic neural network approach*. Elsevier, Amsterdam - NY.
3. Poznyak A, Chairez I, Poznyak T (2019), *A survey on artificial neural networks application for identification and control in environmental engineering: biological and chemical systems with uncertain models*. *Annu Rev Control* 48:250–272.
4. Alejandra Hernandez-Sanchez, Isaac Chairez, Alexander Poznyak, Olga Andrianova. *Dynamic Motion Backstepping Control of Underwater Autonomous Vehicle Based on Averaged Sub-gradient Integral Sliding Mode Method*, *Journal of Intelligent & Robotic Systems*, (2021) 103:48, <https://doi.org/10.1007/s10846-021-01466-3>.
5. A. Poznyak, I. Chairez, A. Anyutin. *Differential Neural Networks Prediction Using Slow and Fast Hybrid Learning: Application to Prognosis of Infections and Deaths of COVID-19 Dynamics*. *Neural Processing Letters*, March 2023, <https://doi.org/10.1007/s11063-023-11216-1>